Errata for Signals and Systems: A MATLAB Integrated Approach

• Page 30, Eqn. (1.55) should be corrected as follows:

$$x(t) = x_r(t) + i x_i(t)$$
 (1.55)

• Page 31, Example 1.4: First displayed equation should be corrected as follows:

$$x(t) = x_r(t) + j x_i(t)$$

• Page 40, Example 1.10: Last displayed equation should be corrected as follows:

$$P_X = \lim_{T \to \infty} \left[\frac{1}{T} \int_{-T/2}^{T/2} x^2(t) dt \right]$$

• Page 66, Eqn. (1.165) should be corrected as follows:

$$x[n] = x_r[n] + j x_i[n]$$
 (1.165)

- Page 88, Problem 1.27, part c: Delete the word "both".
- Page 205, displayed equation for y[0] should be corrected as follows:

$$y[0] = (1 - \alpha) y[-1] + \alpha x[-1]$$

- Page 209, last line above Eqn. (3.59) should be corrected as follows: "...the characteristic equation by z^N to obtain"
- Page 218, Example 3.14: Last displayed equation should be corrected as follows:

$$y_{h}[n] = 1.5 (1 - \alpha) (1 - \alpha)^{n} + 1$$

- Page 222, sentence above Eqn. (3.93) should be modified as follows:
 "... that utilize an intermediate signal w[n] are equivalent to ..."
- Page 245, equation at the bottom of the page should be corrected as follows:

Eqn. (3.15):
$$y[n] = (1+c) y[n-1] - x[n]$$

• Page 248, Eqn. (3.164) should be corrected as follows:

$$a_0 y[n] + a_1 y[n-1] + \dots + a_{N-1} y[n-N+1] + a_N y[n-N] = b_0 x[n] + b_1 x[n-1] + \dots + b_{M-1} x[n-M+1] + b_M x[n-M]$$
(3.164)

- Page 254, Problem 3.4, part a, correct as follows:
 - **a.** Sys₁ $\{x[n]\} = 3x[n]$ and Sys₂ $\{w[n]\} = nw[n]$
- Page 279, displayed equation for a_k should be corrected as follows:

$$a_k = \frac{2}{3} \int_{-0.5}^{0.5} (1) \cos(2\pi kt/3) dt = \frac{2 \sin(2\pi k/3)}{\pi k}$$

• Page 318, Eqn. (4.152) should be corrected as follows:

$$\theta(f) = \begin{cases} \beta(f) & \text{if } B(f) \ge 0\\ \beta(f) \pm \pi & \text{if } B(f) < 0 \end{cases}$$
(4.152)

• Page 426, Eqns. (5.45) and (5.46) should be corrected as follows:

$$\tilde{x}[-n] = \tilde{x}[n]$$
, all n implies that $\operatorname{Im}\{\tilde{c}_k\} = 0$, all k (5.45)

$$\tilde{x}[-n] = -\tilde{x}[n]$$
, all n implies that $\text{Re}\left\{\tilde{c}_k\right\} = 0$, all k (5.46)

• Page 427, Table 5.1: Some values in the table have incorrect signs. Corrected table is given below:

k	$ ilde{c}_k$	$ \tilde{c}_k $	$ ilde{ heta}_k$
0	0.0	0.0	N/A
1	-j0.4710	0.4710	$-\pi/2$
2	j0.0625	0.0625	$\pi/2$
3	j0.0290	0.0290	$\pi/2$
4	0.0	0.0	N/A
5	-j0.0290	0.0290	$-\pi/2$
6	-j0.0625	0.0625	$-\pi/2$
7	j0.4710	0.4710	$\pi/2$

• Pages 447,449, Example 5.16: Change the signal in the problem statement to $x[n] = \alpha^{n-1} u[n-1]$. Correspondingly, the top two equations on Page 458 become

$$\alpha^{n} u[n] \xrightarrow{\mathscr{F}} \frac{1}{1 - \alpha e^{-j\Omega}} \quad \text{and} \quad X(\Omega) = \mathscr{F} \left\{ \alpha^{n-1} u[n-1] \right\} = \frac{e^{-j\Omega}}{1 - \alpha e^{-j\Omega}}$$

• Page 457, 458 Example 5.18: Change the signal in the problem statement to $x[n] = n \alpha^n u[n]$. Correspondingly, the top two equations on Page 458 become

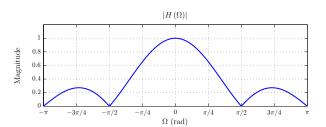
$$\alpha^{n} u[n] \stackrel{\mathscr{F}}{\longleftrightarrow} \frac{1}{1 - \alpha e^{-j\Omega}} \quad \text{and} \quad n\alpha^{n} u[n] \stackrel{\mathscr{F}}{\longleftrightarrow} j\frac{d}{d\Omega} \left[\frac{1}{1 - \alpha e^{-j\Omega}} \right]$$

• Page 480, Example 5.28:

Two unnumbered equations are missing a 1/N factor, and should be corrected as follows:

$$\begin{split} H\left(\Omega\right) &= \frac{1}{N} \, \frac{1 - e^{-j\Omega N}}{1 - e^{-j\Omega}} \\ H\left(\Omega\right) &= \frac{e^{-j\Omega N/2} \left(e^{j\Omega N/2} - e^{-j\Omega N/2}\right)}{N \, e^{-j\Omega/2} \left(e^{j\Omega/2} - e^{-j\Omega/2}\right)} \\ &= \frac{\sin\left(\Omega N/2\right)}{N \sin\left(\Omega/2\right)} \, e^{-j\Omega\left(N-1\right)/2} \end{split}$$

As a result, the vertical axis scaling of the magnitude graph in Fig. 5.41(a) should be modified as follows:



- Page 483, Eqns. (5.235) and (5.236): Change ω_0 to Ω_0 .
- · Page 485, unnumbered equation: The extraneous equal sign at the end of the equation should be removed.
- Page 507, Table 5.5: Some of the signs are reversed. The correct Table 5.5 should be as follows:

k	X[k]	H[k]	Y[k]
0	8.0000+j0.0000	15.0000+j 0.0000	120.0000+j 0.0000
1	5.3992 - j 0.6735	2.5000 - j 3.4410	11.1803- <i>j</i> 20.2622
2	-6.8992 + j 7.4697	2.5000 - j 0.8123	-11.1803+j24.2784
3	-6.8992 - j 7.4697	2.5000+j 0.8123	-11.1803- <i>j</i> 24.2784
4	5.3992 + j 0.6735	2.5000+j3.4410	11.1803+ <i>j</i> 20.2622

- Page 516, MATLAB Exercise 5.3, last sentence: Change the phrase "circular convolution" to "periodic convolution".
- Page 591, Problem 6.14 should be corrected as follows: "The signal $x_a(t) = \cos(150\pi t)$ is ..."
- Page 663, unnumbered dissplayed equation in the middle of the page: Change z to s.

$$H\left(s\right) = \frac{B\left(s\right)}{A\left(s\right)} = \frac{b_{M}s^{M} + b_{M-1}s^{M-1} + \dots + b_{1}s + b_{0}}{a_{N}s^{N} + a_{N-1}s^{N-1} + \dots + a_{1}s + a_{0}}$$

• Page 709, MATLAB Exercise 7.8, second line of MATLAB code from the top should be corrected as follows:

$$>> pls = [-1, -2, -3];$$

• Page 726, Eqn. (8.1) should be corrected as follows:

$$X(z) = \dots + x[-2]z^{2} + x[-1]z^{1} + x[0] + x[1]z^{-1} + x[2]z^{-2} + \dots$$
(8.1)

- Page 821, Example 8.44, first line: Change the word "cascade" to "parallel".
- Page 911, 4-th line of MATLAB code should be corrected as follows:

$$\rightarrow$$
 H = C/z*rsm*B+D

• Page 973, displayed equation for $\Theta(\Omega)$ should be corrected as follows:

$$\Theta(\Omega) = -1/2\Omega$$

• Page 975, Eqns. (10.173) and (10.174) should be corrected as follows:

$$h_T[n] = \begin{cases} h_d[n], & -M \le M \\ 0, & \text{otherwise} \end{cases}$$
 (10.173)

$$H_T(\Omega) = \sum_{n = -\infty}^{\infty} h_T[n] e^{-j\Omega n} = \sum_{n = -M}^{M} h_d[n] e^{-j\Omega n}$$
 (10.174)

• Page 1019, Fig. 11.10: Vertical axis should be labeled m(t).